

The KMS Condition for the homoclinic equivalence relation and Gibbs probabilities

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Abstract

D. Ruelle considered a general setting where he is able to characterize equilibrium states for Hölder potentials based on properties of conjugating homeomorphism in the so called Smale spaces. On this setting he also shows a relation of KMS states of C^* -algebras with equilibrium probabilities of Thermodynamic Formalism. A later paper by N. Haydn and D. Ruelle presents a shorter proof of this equivalence.

Here we consider similar problems but now on the symbolic space $\Omega = \{1, 2, \dots, d\}^{\mathbb{Z}-\{0\}}$ and the dynamics will be given by the shift τ . In the case of potentials depending on a finite coordinates we will present a simplified proof of the equivalence mentioned above which is the main issue of the papers by D. Ruelle and N. Haydn. The class of conjugating homeomorphism is explicit and reduced to a minimal set of conditions.

We also present with details (following D. Ruelle) the relation of these probabilities with the KMS dynamical C^* -state on the C^* -Algebra associated to the groupoid defined by the homoclinic equivalence relation.

The topics presented here are not new but we believe the main ideas of the proof of the results by Ruelle and Haydn will be quite transparent in our exposition.

1 Introduction

D. Ruelle in [20] considered a general setting (which includes hyperbolic diffeomorphisms on manifolds) where he is able to describe a formulation of the concept of Gibbs state based on **conjugating homeomorphism** in the

so called Smale spaces. On this setting he shows a relation of KMS states of C^* -algebras with Hölder equilibrium probabilities of Thermodynamic Formalism. Part of the formulation of this relation requires the use of a non trivial result by N. Haydn (see [10]). Later, the paper [11] by N. Haydn and D. Ruelle presents a shorter proof of the equivalence.

Here we consider similar problems but now on the symbolic space and the dynamics will be given by the shift. We will present a simplified proof of the equivalence mentioned above. The main result of this chapter is Theorem 18 on section 5. One can get a characterization of the equilibrium probability for a potential defined on the lattice $\{1, 2, \dots, d\}^{\mathbb{Z}-\{0\}}$ without using the Ruelle operator (which acts on the lattice $\{1, 2, \dots, d\}^{\mathbb{N}}$). The probability we get is invariant for the action of the shift τ acting on $\{1, 2, \dots, d\}^{\mathbb{Z}-\{0\}}$.

The proof of this result will take several subsequent sections.

In section 8 we show the relation of these probabilities with the KMS dynamical C^* -state on the C^* -Algebra associated to the groupoid defined by the homoclinic equivalence relation. On the initial sections we introduce several results which are necessary for the simplification of the final argument on section 8.

We present several examples helping the reader on the understanding of the main concepts.

On [21] and also on the beginning of the book [1] it is explained the relation of equilibrium states of Thermodynamic Formalism with the corresponding concept in Statistical Physics. The role of KMS C^* -dynamical states on Quantum Statistical Physics is described on [4]. KMS C^* -dynamical states correspond to the DLR probabilities (see [6] for definition) in Statistical Mechanics.

In section 8 we present definitions and properties regarding the C^* -algebra we will consider here.

Working on the symbolic space helps to avoid several technicalities which are required in the case of the study of hyperbolic diffeomorphisms on manifolds (where one have to use stable foliation, the local product structure, etc...).

Our proof consider mainly potentials $A : \{1, 2, \dots, d\}^{\mathbb{Z}-\{0\}} \rightarrow \mathbb{R}$ which depend on a finite number of coordinates. The case of a general Hölder potential (more technical) can be obtained by adapting our reasoning but we will not address this question here.

On the papers [5] and [13] the authors consider among other things a relation of KMS probabilities with eigenprobabilities for the dual of the Ruelle operator (which are not necessarily invariant for the shift). This problem is analyzed on the lattice $\{1, 2, \dots, d\}^{\mathbb{N}}$ which is a different setting that the one we consider here. The equivalence relations are also not related. Despite

some similarities that can be perceived in the statements of the main results obtained in the two settings we point out that the reasoning on the respective proofs are quite different.

Lecture 9 in [7] presents a brief introduction to C^* -Algebras and the KMS condition.

In [8] and [9] a relation of KMS states in a certain C^* -Algebra and eigenprobabilities of the dual of the Ruelle operator is considered.

In a different setting the paper [2] also considers the homoclinic equivalence relation.

2 Conjugating homeomorphisms

In this section $\Omega = \{1, 2, \dots, d\}^{\mathbb{Z}-\{0\}}$ and a general point x on Ω is denoted as

$$x = (\dots, x_{-n}, \dots, x_{-2}, x_{-1} \mid x_1, x_2, \dots, x_n, \dots),$$

$$x_j \in \{1, 2, \dots, d\}, j \in \mathbb{Z}.$$

We consider the dynamics of the shift $\tau : \Omega \rightarrow \Omega$, that is,

$$\tau(\dots, x_{-n}, \dots, x_{-2}, x_{-1} \mid x_1, x_2, \dots, x_n, \dots) = (\dots, x_{-n}, \dots, x_{-2}, x_{-1}, x_1 \mid x_2, \dots, x_n, \dots).$$

We also consider the usual metric d on Ω which is defined in such way that for $x, y \in \Omega$ we set

$$d(x, y) = 2^{-N},$$

$N \geq 0$, where for

$$x = (\dots, x_{-n}, \dots, x_{-1} \mid x_1, \dots, x_n, \dots), y = (\dots, y_{-n}, \dots, y_{-1} \mid y_1, \dots, y_n, \dots),$$

we have $x_j = y_j$, for all j , such that, $-N \leq j \leq N$ and, moreover $x_{N+1} \neq y_{N+1}$, or $x_{-N-1} \neq y_{-N-1}$. Given x, y as above we denote $\vartheta(x, y) = N$, therefore $\vartheta(x, y) = -\log_2(d(x, y))$.

Given $x, y \in \Omega$, we say that $x \sim y$ if

$$\lim_{k \rightarrow +\infty} d(\tau^k x, \tau^k y) = 0$$

and

$$\lim_{k \rightarrow -\infty} d(\tau^k x, \tau^k y) = 0. \quad (1)$$

This means there exists an $N \geq 0$ such that $x_j = y_j$ for $j > N$ and $j < -N$ (note that given $\epsilon > 0$, there exists n such that $2^{-n} < \epsilon \leq 2^{-n+1}$, and if $d(x, y) < \epsilon$, then x and y should coincide for coordinates smaller than n). In

other words, there are only a finite number of i 's such that $x_i \neq y_i$. In this case we say that x and y are homoclinic.

In this way for large $k > 0$ the strings for $\tau^k(x) = z^x$ and $\tau^k(y) = z^y$ are such that $z_j^x = z_j^y$ for j in a large interval $j \in \{-R, -R+1, \dots, -1, 1, \dots, R-1, R\}$, where R is larger with k . Then, $\lim_{k \rightarrow +\infty} d(\tau^k x, \tau^k y) = 0$.

\sim is an equivalence relation and defines the groupoid $G \subset \Omega \times \Omega$ of pairs (x, y) of elements which are related (see for instance [18], [19], [5] or [13]).

Let $\kappa(x, y)$ be the minimum M as above. Therefore $x_{\kappa(x,y)} \neq y_{\kappa(x,y)}$ or $x_{-\kappa(x,y)} \neq y_{-\kappa(x,y)}$. Note that $\vartheta(x, y) \leq \kappa(x, y)$ and could be strictly less. Note that $\kappa(x, y)$ is defined just when $x \sim y$.

Example 1. For example in $\Omega = \{1, 2\}^{\mathbb{Z}-\{0\}}$ take

$$x = (\dots, x_{-n}, \dots, x_{-7}, 1, 2, 2, 1, 2, 2 \mid 1, 2, 1, 2, 1, 1, x_7, \dots, x_n, \dots)$$

and

$$y = (\dots, y_{-n}, \dots, y_{-7}, 1, 2, 2, 1, 2, 2 \mid 1, 2, 1, 1, 1, 2, y_7, \dots, y_n, \dots)$$

where $x_j = y_j$ for $|j| > 6 = \kappa(x, y)$. In this case $d(x, y) = 2^{-3}$ and $N = \vartheta(x, y) = 3$.

Given a Hölder function $U : \Omega \rightarrow \mathbb{R}$ it is easy to see that if x and y are homoclinic, then the following function is well defined

$$V(x, y) = \sum_{n=-\infty}^{\infty} (U(\tau^n(x)) - U(\tau^n(y))). \quad (2)$$

Indded, note that if $x \sim y$, they coincide for large n , then, there exists a constant c , such that, $d(\tau^n(x), \tau^n(y)) \leq c2^{-n}$. If U has Holder exponent α , then, the sum converges absolutely because $\sum_n (2^\alpha)^{-n} < \infty$.

This function satisfies the property

$$V(x, y) + V(y, z) = V(x, z)$$

when $x \sim y \sim z$.

A function V with this property will play an important role in some parts of our reasoning. We will not assume on the first part of this work that V was obtained from a U as above.

Now we will describe a certain class of **conjugating homeomorphism** for the relation \sim (see (1)) described above.

Given two fixed points x and y (y in the class of x) we define the open set $\mathcal{O}_{(x,y)} = B_{\frac{1}{2^{\kappa(x,y)}}}(x) = \{z \in \Omega : d(x, z) < 2^{-\kappa(x,y)+1}\}$.

We will define for each such pair (x, y) a conjugating homeomorphisms $\varphi_{(x,y)}$ which has domain on $\mathcal{O}_{(x,y)}$.

We denote for $m, n \in \mathbb{N}$

$$\overline{x_{-m}x_{-m+1}\dots x_{-1} \mid x_1\dots x_{n-1}x_n} =$$

$$\{z \in \Omega \mid z_j = x_j, j = -m, -m+1, \dots, -1, 1, 2, \dots, n-1, n\},$$

and call it the cylinder determined by the finite string

$$x_{-m}x_{-m+1}\dots x_{-1} \mid x_1\dots x_{n-1}x_n.$$

We will say that a cylinder, or a string, is **symmetric** if $n = m$.

Note that given $x \sim y$

$$\mathcal{O}_{(x,y)} = \overline{x_{-\kappa(x,y)} x_{-\kappa(x,y)+1} \dots x_{-1} \mid x_1 \dots x_{\kappa(x,y)-1} x_{\kappa(x,y)}},$$

and $\mathcal{O}_{(x,y)}$ is a symmetric cylinder.

Now we shall define the main kind of **conjugating homeomorphisms** that we will be using. Given $(x, y) \in G$, let $n = \kappa(x, y)$, we define a conjugating $\varphi = \varphi_{(x,y)}$ with domain

$$\mathcal{O}_{(x,y)} = B_{\frac{1}{2^n}}(x) = \{z \in \Omega : d(x, z) < 2^{-n+1}\} = \overline{x_{-n}x_{-n+1}\dots x_{-1} \mid x_1\dots x_{n-1}x_n},$$

where $\varphi_{(x,y)} : \mathcal{O}_{(x,y)} \rightarrow B_{\frac{1}{2^n}}(y)$ is defined by the expression: z of the form

$$z = (\dots z_{-n-2}z_{-n-1} \mathbf{x}_{-n}\mathbf{x}_{-n+1}\dots\mathbf{x}_{-1} \mid \mathbf{x}_1\dots\mathbf{x}_n z_{n+1}z_{n+2}\dots)$$

goes to

$$\varphi_{(x,y)}(z) = \dots z_{-n-2}z_{-n-1} \mathbf{y}_{-n}\mathbf{y}_{-n+1}\dots\mathbf{y}_{-1} \mid \mathbf{y}_1\dots\mathbf{y}_n z_{n+1}z_{n+2}\dots \quad (3)$$

We shall call these transformations the family of **symmetric conjugating homeomorphisms**. We shall denote by S the set of symmetric conjugating homeomorphisms obtained by considering all pairs of related points x and y .

Note that the homeomorphism $\varphi_{(x,y)}$ transforms the cylinder $\mathcal{O}_{(x,y)} = \overline{x_{-n}x_{-n+1}\dots x_{-1} \mid x_1\dots x_{n-1}x_n}$ in the cylinder $\overline{y_{-n}y_{-n+1}\dots y_{-1} \mid y_1\dots y_{n-1}y_n}$.

The graph of $\varphi_{(x,y)}$ is on G .

A more explicit formulation of the concept of symmetric conjugating homeomorphism will be presented on next section via expressions (6) and (7).

Example 2. Consider

$$x = (...1121122221 \ 11|21 \ 2122122211...)$$

and

$$y = (...1121122221 \ 12|12 \ 2122122211...)$$

in this case $\kappa(x, y) = 2$, and for z of the form

$$z = (...z_{-4} z_{-3} \ 11|21 \ z_3 z_4 z_5...)$$

we get

$$\varphi_{(x,y)}(z) = (...z_{-4} z_{-3} \ 12|12 \ z_3 z_4 z_5...).$$

It is easy to see that the family of symmetric conjugating homeomorphisms we define above has the following properties: given $x \sim y$

- a) $\varphi_{(x,y)} : \mathcal{O}_{(x,y)} \subset \Omega \rightarrow \Omega$ is an homeomorphism over its image
- b) $\varphi_{(x,y)}(x) = y$, and
- c) $\lim_{k \rightarrow \infty} d(\tau^k(z), \tau^k(\varphi_{(x,y)}(z))) = 0$ and $\lim_{k \rightarrow -\infty} d(\tau^k(z), \tau^k(\varphi_{(x,y)}(z))) = 0$.

Item c) implies that z and $\varphi_{(x,y)}(z)$ are on the same homoclinic class.

3 C^* -Gibbs states and Radon-Nikodym derivative

We consider the groupoid $G \subset \Omega \times \Omega$ of all pair of points which are related by the homoclinic equivalence relation.

We consider on G the topology generated by sets of the form

$$\{ (z, \varphi_{(x,y)}(z)) \mid \text{where } z \in \mathcal{O}_{(x,y)} \text{ with } x \sim y \}.$$

This topology is Hausdorff (see [20]).

Now consider a continuous function $V : G \rightarrow \mathbb{R}$ such that

$$V(x, y) + V(y, z) = V(x, z), \tag{4}$$

for all related x, y, z . Note that this implies that $V(x, x) = 0$ and $V(x, y) = -V(y, x)$.

Here we call V a modular function.

Under some other notation the function $\delta(x, y) = e^{V(x,y)}$ is called a modular function (or, a cocycle).

Definition 3. Given a function $V : G \rightarrow \mathbb{R}$ as above we say that a probability measure α on Ω is a **C^* -Gibbs probability** with respect to the parameter $\beta \in \mathbb{R}$ and V , if for any $x \sim y$

$$\int_{O(x,y)} \exp(-\beta V(z, \varphi_{(x,y)}(z))) f(\varphi_{(x,y)}(z)) d\alpha(z) = \int_{\varphi_{(x,y)}(O(x,y))} f(z) d\alpha(z), \quad (5)$$

for every continuous function $f : \Omega \rightarrow \mathbb{C}$ (and conjugated homeomorphism $(O(x,y), \varphi_{(x,y)})$).

We will show on section 8 a natural relation of this probability α with the C^* -dynamical state on a certain C^* -algebra. This is the reason for such terminology.

The above definition was taken from [20]. This is a version of the Renault-Radon-Nikodym condition (Def. 1.3.15 in [18]).

It is easy to see that the above definition is equivalent to say that: given any pair of finite strings

$$x_{-n}x_{-n+1}\dots x_{-1}, x_1\dots x_{n-1}x_n \quad \text{and} \quad y_{-n}y_{-n+1}\dots y_{-1} y_1\dots y_{n-1}y_n,$$

$n \in \mathbb{N}$, the transformation

$$\varphi : \overline{x_{-n}x_{-n+1}\dots x_{-1} \mid x_1\dots x_{n-1}x_n} \rightarrow \overline{y_{-n}y_{-n+1}\dots y_{-1} \mid y_1\dots y_{n-1}y_n} \quad (6)$$

defined by the expression:

$$\varphi(z) = (\dots z_{-n-2}z_{-n-1} \mid y_{-n}y_{-n+1}\dots y_{-1} \mid y_1\dots y_n \mid z_{n+1}z_{n+2}\dots), \quad (7)$$

where

$$z = (\dots z_{-n-2}z_{-n-1} \mid z_{-n}z_{-n+1}\dots z_{-1} \mid z_1\dots z_n \mid z_{n+1}z_{n+2}\dots),$$

is such that for any continuous function $f : \overline{y_{-n}y_{-n+1}\dots y_{n-1}y_n} \rightarrow \mathbb{R}$

$$\int_{\overline{x_{-n}x_{-n+1}\dots \mid \dots x_{n-1}x_n}} e^{-\beta V(z, \varphi(z))} f(\varphi(z)) d\alpha(z) = \int_{\overline{y_{-n}y_{-n+1}\dots \mid \dots y_{n-1}y_n}} f(z) d\alpha(z). \quad (8)$$

Note in particular that by taking $f = 1$ we get

$$\int_{\overline{x_{-n}x_{-n+1}\dots \mid \dots x_{n-1}x_n}} e^{-\beta V(z, \varphi(z))} d\alpha(z) = \int_{\overline{y_{-n}y_{-n+1}\dots \mid \dots y_{n-1}y_n}} d\alpha(z). \quad (9)$$

In the moment we only consider symmetric conjugating homeomorphisms of the form (7).

We will show on section 5 a relation of the C^* -Gibbs probabilities α with the **Gibbs (equilibrium) probabilities** of Thermodynamic Formalism.

In a more explicit formulation α is such that given any conjugating homeomorphism $(O_{(x,y)}, \varphi_{(x,y)})$ of the form (6), and continuous function $f : \Omega \rightarrow \mathbb{C}$

$$\begin{aligned} & \int_{O_{(x,y)}} e^{-\beta V(z, \varphi_{(x,y)}(z))} f(\varphi_{(x,y)}(z)) d\alpha(z) = \\ & \int_{O_{(x,y)}} e^{-\beta V((\dots z_{-n}, \dots, z_{-1} | z_1, \dots, z_n, \dots), (\dots z_{-n-1} y_{-n}, \dots, y_{-1} | y_1, \dots, y_n, z_{n+1}, \dots))} f(\varphi_{(x,y)}(z)) d\alpha(z) = \\ & \int_{\varphi_{(x,y)}(O_{(x,y)})} f(z) d\alpha(z). \end{aligned} \quad (10)$$

In this case, clearly the Radon-Nikodym derivative of the change of coordinates φ is

$$e^{-\beta V((\dots z_{-n}, \dots, z_{-1} | z_1, \dots, z_n, \dots), (\dots z_{-n-1} y_{-n}, \dots, y_{-1} | y_1, \dots, y_n, z_{n+1}, \dots))}.$$

In order to simplify the notation sometimes on the text we will consider the value $\beta = 1$.

We will consider a larger class of conjugating homeomorphisms.

Definition 4. *Given n and m and pair of finite strings*

$$x_{-n} x_{-n+1} \dots x_{-1}, x_1 \dots x_{m-1} x_m \quad \text{and} \quad y_{-n} y_{-n+1} \dots y_{-1} y_1 \dots y_{n-1} y_m, \quad (11)$$

$n, m \in \mathbb{N}$, the transformation

$$\varphi : \overline{x_{-n} x_{-n+1} \dots x_{m-1} x_m} \rightarrow \overline{y_{-n} y_{-n+1} \dots y_{m-1} y_m} \quad (12)$$

defined by the expression:

$$\varphi(z) = (\dots z_{-n-2} z_{-n-1} \mathbf{Y}_{-n} \mathbf{Y}_{-n+1} \dots \mathbf{Y}_{-1} | \mathbf{Y}_1 \dots \mathbf{Y}_m z_{m+1} z_{m+2} \dots), \quad (13)$$

where

$$z = (\dots z_{-n-2} z_{-n-1} \mathbf{X}_{-n} \mathbf{X}_{-n+1} \dots \mathbf{X}_{-1} | \mathbf{X}_1 \dots \mathbf{X}_m z_{m+1} z_{m+2} \dots),$$

is called a **non-symmetric conjugating homeomorphism** associated to the pair (11).

Proposition 6 claims that if α is a C^* -Gibbs probability, then the relation (10) is satisfied for a bigger class of φ transformations, i.e. not necessarily symmetric. Before that we shall provide the reader with an example of idea of the proof.

Example 5. Consider the non-symmetric conjugating homeomorphism $\varphi : \overline{0|11} \rightarrow \overline{1|10}$ given by

$$\varphi(\dots z_{-3} z_{-2} 0 | 11 z_3 \dots) = \dots z_{-3} z_{-2} 1 | 10 z_3 \dots$$

we shall prove that if α is a C^* -Gibbs measure then relation (5) is valid for φ . This is actually straightforward, first divide the domain and image of the function into symmetric cylinders, and in these cylinders apply relation (10). So in this case consider $\varphi_0 : \overline{00|11} \rightarrow \overline{01|10}$, and $\varphi_1 : \overline{10|11} \rightarrow \overline{11|10}$ such that

$$\varphi_a(\dots z_{-3} a 0 | 11 z_3 \dots) = (\dots z_{-3} a 1 | 10 z_3 \dots)$$

for $a = 0$ or $a = 1$. Now notice that

$$\begin{aligned} & \int_{\overline{0|11}} e^{-\beta V(x, \varphi(x))} f(\varphi(x)) d\alpha(x) = \\ & \int_{\overline{00|11}} e^{-\beta V(x, \varphi(x))} f(\varphi(x)) d\alpha(x) + \int_{\overline{10|11}} e^{-\beta V(x, \varphi(x))} f(\varphi(x)) d\alpha(x) = \\ & \int_{\overline{00|11}} e^{-\beta V(x, \varphi_0(x))} f(\varphi(x)) d\alpha(x) + \int_{\overline{10|11}} e^{-\beta V(x, \varphi_1(x))} f(\varphi(x)) d\alpha(x) \stackrel{(10)}{=} \\ & \int_{\overline{01|10}} f(x) d\alpha(x) + \int_{\overline{11|10}} f(x) d\alpha(x) = \int_{\overline{1|10}} f(x) d\alpha(x). \end{aligned}$$

This claim proves that relation (10) is valid for this conjugating.

Proposition 6. Assume α is C^* -Gibbs for V as in (10), then for any non-symmetric homeomorphism (φ, \mathcal{O}) , as defined on (13), we have that for $n, m \in \mathbb{N}$, the transformation

$$\begin{aligned} & \int_{\overline{x_{-n} x_{-n+1} \dots x_{-1} | x_1 \dots x_{m-1} x_m}} e^{-\beta V(z, \varphi(z))} f(\varphi(z)) d\alpha(z) = \\ & \int_{\mathcal{O}} e^{-\beta V(\dots z_{-n-1} z_{-n}, \dots, z_{-1} | z_1, \dots, z_m, z_{m+1} \dots), (\dots z_{-n-1} y_{-n}, \dots, y_{-1} | y_1, \dots, y_m, z_{m+1}, \dots)} f(\varphi(z)) d\alpha(z) = \\ & \int_{\overline{y_{-n} y_{-n+1} \dots y_{-1} | y_1 \dots y_{m-1} y_m}} f(z) d\alpha(z). \end{aligned} \tag{14}$$

We leave the proof (which is similar to the reasoning of example 5) for the reader.

As a particular case we get

$$\int_{\overline{|x_1 \dots x_m|}} e^{-\beta V(z, \varphi(z))} f(\varphi(z)) d\alpha(z) = \int_{\overline{|y_1 \dots y_m|}} f(z) d\alpha(z). \quad (15)$$

for given $\overline{|x_1 \dots x_m|}$, $\overline{|y_1 \dots y_m|}$ and the corresponding conjugating homeomorphism φ .

It is possible to consider more general forms of conjugating homeomorphisms as described on the next example.

Example 7. Consider the homeomorphism $\varphi : \overline{112|2} \rightarrow \overline{1|122}$ given by

$$\varphi(\dots z_{-4} 112|2 z_2 z_3 z_4 \dots) = (\dots z_{-4} z_2 z_3 1|122 z_4 \dots).$$

Note that $\overline{112|2}$ is translation by τ^{-2} of the set $\overline{1|122}$.

As in the previous example we will prove that if α is a C^* -Gibbs probability then relation (10) is also valid for such φ and $\mathcal{O} = \overline{112|2}$. First consider the conjugating homeomorphisms, φ_1 , φ_2 , φ_3 and φ_4 , given by

$$\varphi_1(\dots z_{-4} 112|2 \mathbf{11} z_4 \dots) = (\dots z_{-4} \mathbf{111}|122 z_4 \dots),$$

$$\varphi_2(\dots z_{-4} 112|2 \mathbf{12} z_4 \dots) = (\dots z_{-4} \mathbf{121}|122 z_4 \dots),$$

$$\varphi_3(\dots z_{-4} 112|2 \mathbf{21} z_4 \dots) = (\dots z_{-4} \mathbf{211}|122 z_4 \dots),$$

$$\varphi_4(\dots z_{-4} 112|2 \mathbf{22} z_4 \dots) = (\dots z_{-4} \mathbf{221}|122 z_4 \dots).$$

Therefore we have that

$$\begin{aligned} & \int_{\overline{112|2}} e^{V(x, \varphi(x))} f(\varphi(x)) d\alpha(x) = \\ & \int_{\overline{112|211}} e^{V(x, \varphi(x))} f(\varphi(x)) + \int_{\overline{112|212}} e^{V(x, \varphi(x))} f(\varphi(x)) + \\ & \int_{\overline{112|221}} e^{V(x, \varphi(x))} f(\varphi(x)) + \int_{\overline{112|222}} e^{V(x, \varphi(x))} f(\varphi(x)) = \\ & \int_{\overline{112|211}} e^{V(x, \varphi_1(x))} f(\varphi_1(x)) + \int_{\overline{112|212}} e^{V(x, \varphi_2(x))} f(\varphi_2(x)) + \\ & \int_{\overline{112|221}} e^{V(x, \varphi_3(x))} f(\varphi_3(x)) + \int_{\overline{112|222}} e^{V(x, \varphi_4(x))} f(\varphi_4(x)) = \end{aligned}$$

$$\int_{\overline{111|122}} f(x) + \int_{\overline{121|122}} f(x) + \int_{\overline{211|122}} f(x) + \int_{\overline{221|122}} f(x) = \int_{\overline{1|122}} f d\alpha(x)$$

where some of the $d\alpha$ were omitted. Since we proved that

$$\int_{\overline{112|2}} e^{V(x,\varphi(x))} f(\varphi(x)) d\alpha(x) = \int_{\overline{1|122}} f d\alpha(x)$$

for any continuous function f then we have that relation (10) is satisfied.

In analogous way as in last example one can define a conjugating φ such that

$$\varphi : \overline{x_{-n} \dots \mathbf{X}_{-r} \dots \mathbf{X}_{-1} | x_1 \dots x_m} \rightarrow \overline{x_{-n} x_{-n+1} \dots x_{-r-1} | \mathbf{X}_{-r} \dots \mathbf{X}_{-1} x_1 \dots x_m}.$$

We will consider such transformation φ in the next result.

Proposition 8. *Assume α is C^* -Gibbs for V as in (10), then for $n, m \in \mathbb{N}$, and $0 < r$, such that, $r \leq n$, we get*

$$\int_{\overline{x_{-n} x_{-n+1} \dots x_{-r-1} \mathbf{X}_{-r} \mathbf{X}_{-r+1} \dots \mathbf{X}_{-1} | x_1 \dots x_{m-1} x_m}} e^{-\beta V(z,\varphi(z))} f(\varphi(z)) d\alpha(z) = \int_{\overline{x_{-n} x_{-n+1} \dots x_{-r-1} | \mathbf{X}_{-r} \mathbf{X}_{-r+1} \dots \mathbf{X}_{-1} x_1 \dots x_{m-1} x_m}} f(z) d\alpha(z), \quad (16)$$

where φ is of the form (13).

Proof: The proof is similar to the reasoning of example 7. One just has to consider the homeomorphisms

$$\varphi(\dots z_{-n-r-1} z_{-n-r} \dots z_{-n-1} x_{-n} x_{-n+1} \dots x_{-1} | x_1 \dots x_{m-1} x_m \mathbf{Z}_{\mathbf{m}+1} \dots \mathbf{Z}_{\mathbf{m}+r} z_{\mathbf{m}+r+1} \dots) = (\dots z_{-n-r} \mathbf{Z}_{\mathbf{m}+1} \dots \mathbf{Z}_{\mathbf{m}+r} x_{-n} x_{-n+1} \dots x_{-r-1} | x_{-r} x_{-r+1} \dots x_{-1} x_1 \dots x_{m-1} x_m z_{\mathbf{m}+r+1} \dots).$$

Note that

$$\frac{\tau^{-r}(\overline{x_{-n} x_{-n+1} \dots x_{-1} | x_1 \dots x_{m-1} x_m})}{\overline{x_{-n} x_{-n+1} \dots x_{-r-1} | x_{-r} x_{-r+1} \dots x_{-1} x_1 \dots x_{m-1} x_m}}.$$

□

We want to show that α is C^* -Gibbs for V , then, the pullback $\rho = \tau^*(\alpha)$ is also C^* -Gibbs for V .

The next example will help to understand the main reasoning for the proof of the above claim.

Example 9. Suppose $V(x, y)$ is defined when $x \sim y$. Assume that for all x, y on the groupoid we have that $V(x, y) = V(\tau(x), \tau(y))$.

Given α consider the pull back $\rho = \tau^*(\alpha)$.

Consider

$$\varphi : \overline{11|21} \rightarrow \overline{21|12},$$

where

$$\varphi(\dots x_{-4} x_{-3} 11|21 x_3 x_4 \dots) = (\dots x_{-4} x_{-3} 21|12 x_3 x_4 \dots),$$

and

$$\varphi_1 : \overline{112|1} \rightarrow \overline{211|2},$$

where

$$\varphi_1(\dots x_{-5} x_{-4} 112|1 x_2 x_3 \dots) = (\dots x_{-5} x_{-4} 211|2 x_2 x_3 \dots).$$

If for any continuous function g we have that

$$\int_{\overline{11|21}} e^{V(x, \varphi(x))} g(\varphi(x)) d\alpha(x) = \int_{\overline{21|12}} g(x) d\alpha(x),$$

then, for any continuous function f we have that

$$\int_{\overline{112|1}} e^{V(x, \varphi_1(x))} f(\varphi_1(x)) d\rho(x) = \int_{\overline{211|2}} f(x) d\rho(x).$$

In fact both properties are equivalent.

Note first that $\varphi_1 \circ \tau = \tau \circ \varphi$.

Moreover, $V(\tau(x), \varphi_1(\tau(x))) = V(\tau(x), \tau(\varphi_1(x))) = V(x, \varphi_1(x))$ by hypothesis.

Therefore,

$$\begin{aligned} & \int_{\overline{112|1}} e^{V(x, \varphi_1(x))} f(\varphi_1(x)) d\rho(x) = \\ & \int I_{\overline{112|1}}(x) e^{V(x, \varphi_1(x))} f(\varphi_1(x)) d\rho(x) = \\ & \int I_{\overline{112|1}}(\tau(x)) e^{V(\tau(x), \varphi_1(\tau(x)))} f(\varphi_1(\tau(x))) d\alpha(x) = \\ & \int I_{\overline{112|1}}(\tau(x)) e^{V(x, \varphi_1(x))} f(\varphi_1(\tau(x))) d\alpha(x) = \\ & \int I_{\overline{112|1}}(\tau(x)) e^{V(x, \varphi_1(x))} f(\tau(\varphi_1(x))) d\alpha(x) = \\ & \int I_{\overline{11|21}}(x) e^{V(x, \varphi_1(x))} f(\tau(\varphi_1(x))) d\alpha(x) = \end{aligned}$$

$$\begin{aligned}
& \int_{\overline{11|21}} e^{V(x, \varphi_1(x))} f(\tau(\varphi(x))) d\alpha(x) = \\
& \int_{\overline{21|12}} f(\tau(x)) d\alpha(x) = \\
& \int I_{\overline{21|12}}(x) f(\tau(x)) d\alpha(x) = \\
& \int I_{\overline{21|12}}(\tau^{-1} \circ \tau)(x) f(\tau(x)) d\alpha(x) = \\
& \int I_{\overline{21|12}}(\tau^{-1}(x)) f(x) d\rho(x) = \\
& \int_{\overline{211|2}} f(x) d\rho(x).
\end{aligned}$$

Above we took $g = f \circ \tau$.

From the above reasoning we get that both properties are equivalent.

Proposition 10. *If α is C^* -Gibbs for V , and $V(x, y) = V(\tau(x), \tau(y))$, for all $x, y \in G$, then, the pull back $\rho = \tau^*(\alpha)$ is also C^* -Gibbs for V .*

Proof: Suppose α is C^* -Gibbs for V .

The reasoning of the proof is just a generalization of the argument used on last example.

Consider for $r, s > 0$

$$\varphi : \overline{a_{-r} \dots a_{-1} | a_1 a_2 \dots a_s} \rightarrow \overline{b_{-r} \dots b_{-1} | b_1 b_2 \dots b_s},$$

where

$$\begin{aligned}
& \varphi(\dots x_{-r+2} x_{-r+1} a_{-r} \dots a_{-1} | a_1 a_2 \dots a_s x_{s+1} x_{s+2} \dots) = \\
& (\dots x_{-r+2} x_{-r+1} b_{-r} \dots b_{-1} | b_1 b_2 \dots b_s x_{s+1} x_{s+2} \dots),
\end{aligned}$$

and

$$\varphi_1 : \overline{a_{-r} \dots a_{-1} a_1 | a_2 \dots a_s} \rightarrow \overline{b_{-r} \dots b_{-1} b_1 | b_2 \dots b_s},$$

where

$$\begin{aligned}
& \varphi(\dots x_{-r+2} x_{-r+1} a_{-r} \dots a_{-1} a_1 | a_2 \dots a_s x_{s+1} x_{s+2} \dots) = \\
& (\dots x_{-r+2} x_{-r+1} b_{-r} \dots b_{-1} b_1 | b_2 \dots b_s x_{s+1} x_{s+2} \dots),
\end{aligned}$$

Adapting the argument of last example one can easily show that if for any continuous function g we have that

$$\int_{\overline{a_{-r} \dots a_{-1} | a_1 a_2 \dots a_s}} e^{V(x, \varphi(x))} g(\varphi(x)) d\alpha(x) = \int_{\overline{b_{-r} \dots b_{-1} | b_1 b_2 \dots b_s}} g(x) d\alpha(x), \quad (17)$$

then, for any continuous function f we have that

$$\int_{a_{-r}\dots a_{-1}a_1|a_2\dots a_s} e^{V(x,\varphi_1(x))} f(\varphi_1(x)) d\rho(x) = \int_{b_{-r}\dots b_{-1}b_1|b_2\dots b_s} f(x) d\rho(x). \quad (18)$$

As α is C^* -Gibbs for V , then (18) is true for any f . From (18) it follows that ρ is C^* -Gibbs for V .

We point out that it is equivalent to ask the C^* -Gibbs property for V taking symmetric cylinders or taking not symmetric cylinders (this is implicit on the proof of Proposition 8). □

4 Modular functions and potentials

As we mentioned before given a Hölder function $U : \Omega \rightarrow \mathbb{R}$ there is a natural way (described by (2)) to get a continuous function V satisfying the property (4).

We suppose now that V is such that $V(x, y) = \sum_{k=-\infty}^{\infty} [U(\tau^k(x)) - U(\tau^k(y))]$, when $x \sim y$, where $U : \Omega \rightarrow \mathbb{R}$ is Hölder (see (2)). The function U will sometimes be called a **potential**. We shall also suppose that U is a finite range potential, or equivalently that it depends on a finite number of positive coordinates, that is, there is $k \in \mathbb{N}$ and a function $f : \{1, \dots, d\}^k \rightarrow \mathbb{R}$, such that, for all $x \in \Omega$ we get

$$U(x) = U(\dots x_{-n} x_{-n+1} \dots x_{-2} x_{-1} | x_1 x_2 \dots x_{m-1} x_m \dots) = f(x_1, x_2, \dots, x_k), \quad (19)$$

for this fixed f and $k > 0$, where $U : \Omega \rightarrow \mathbb{R}$. In this case we say that U depends on k coordinates.

Note that such V satisfies $V(x, y) = V(\tau(x), \tau(y))$ and then Proposition 10 can be applied.

Remark 1: By abuse of language we can write $U : \{1, 2, \dots, d\}^{\mathbb{N}} \rightarrow \mathbb{R}$.

If $x \sim y$ it isn't hard to see that there is a finite $M > 0$, such that,

$$V(x, y) = \sum_{k=-\infty}^{\infty} [U(\tau^k(x)) - U(\tau^k(y))] = \sum_{k=-M}^M [U(\tau^k(x)) - U(\tau^k(y))].$$

In this way, if $z \sim \varphi(z)$, then,

$$V(z, \varphi(z)) = \sum_{k=-M}^M U(\tau^k(z)) - \sum_{k=-M}^M U(\tau^k(\varphi(z))) = \sum_{k=-M}^M [U(\tau^k(z)) - U(\tau^k(\varphi(z)))].$$

Therefore, in this case, equation (10) means

$$\int_{x_{-n}, \dots, x_{-1} \mid x_1, x_2, \dots, y_n} e^{\sum_{k=-M}^M U(\tau^k(\varphi(z))) - \sum_{k=-M}^M U(\tau^k(z))} f(\varphi(z)) d\alpha(z) = \int_{y_{-n}, \dots, y_{-1} \mid y_1, y_2, \dots, y_n} f(z) d\alpha(z) \quad (20)$$

If α is C^* -Gibbs for V , and $V(z, \varphi(z)) = \sum_{k=-\infty}^{+\infty} U(z) - U(\varphi(z))$ we also say **by abuse of language that α is C^* -Gibbs for $U : \Omega \rightarrow \mathbb{R}$.**

Definition 11. *Given a function $V : G \rightarrow \mathbb{R}$, $V(x, y) = \sum_{k=-\infty}^{\infty} [U(\tau^k(x)) - U(\tau^k(y))]$, with U of Hölder class, we say that a probability measure α on Ω is the **quasi C^* -Gibbs probability** with respect to the parameter $\beta \in \mathbb{R}$ and U , if there exists constants $d_1 > 0$ and $d_2 > 0$, such that, for any $x \sim y$ and any $O_{(x,y)}$,*

$$\begin{aligned} d_1 \int_{O_{(x,y)}} \exp(-\beta V(z, \varphi_{(x,y)}(z))) g(\varphi_{(x,y)}(z)) d\alpha(z) &\leq \\ \int_{\varphi_{(x,y)}(O_{(x,y)})} g(z) d\alpha(z) &\leq d_2 \int_{O_{(x,y)}} \exp(-\beta V(z, \varphi_{(x,y)}(z))) g(\varphi_{(x,y)}(z)) d\alpha(z) \end{aligned} \quad (21)$$

for every every continuous function $g : \Omega \rightarrow \mathbb{C}$ (and symmetric conjugated homeomorphism $(O_{(x,y)}, \varphi_{(x,y)})$).

In the same way as before one can extend the above property for symmetric conjugated homeomorphisms to non symmetric conjugated homeomorphisms.

A C^* -Gibbs probability is a quasi C^* -Gibbs probability.

We say that a potential $\tilde{U} : \{1, 2, \dots, d\}^{\mathbb{N}} \rightarrow \mathbb{R}$ - which depends on a finite number of coordinates - is **normalized**, if for k large enough and for any (x_1, x_2, \dots, x_k) we get $\sum_{j=1}^d e^{\tilde{U}(j, x_1, \dots, x_{k-1})} = 1$ - in particularly, we get $e^{\tilde{U}(x)} = e^{\tilde{U}(x_1, \dots, x_k)} < 1$ for all $x = (x_1, x_2, \dots) \in \{1, 2, \dots, d\}^{\mathbb{N}}$.

From this follows that for any $w = (w_1, w_2, \dots, w_m, \dots) \in \{1, 2, \dots, d\}^{\mathbb{N}}$ and $n \in \mathbb{N}$,

$$\sum_{z_1, z_2, \dots, z_n=1}^d e^{\sum_{j=0}^{n-1} \tilde{U}(\sigma^j(z_1, z_2, \dots, z_n, w_1, w_2, w_3, \dots, w_m, \dots))} = 1$$

where σ is the shift acting on $\{1, 2, \dots, d\}^{\mathbb{N}}$.

Suppose for such U that α is quasi C^* -Gibbs for U (satisfies the double inequality (21) for any continuous g). This implies in particular that there exist $d_1, d_2 > 0$, such that, for any cylinders of the form $\overline{|x_1^0, x_2^0, \dots, x_s^0}$ and $\overline{|y_1^0, y_2^0, \dots, y_s^0}$, and a function φ , such that,

$$d_1 \int_{\overline{|x_1^0, x_2^0, \dots, x_s^0}} e^{-\beta V(z, \varphi(z))} g(\varphi_{(x,y)}(z)) d\alpha(z) \leq \int_{\overline{|y_1^0, y_2^0, \dots, y_s^0}} g(z) d\alpha(z) \leq d_2 \int_{\overline{|x_1^0, x_2^0, \dots, x_s^0}} e^{-\beta V(z, \varphi(z))} g(\varphi_{(x,y)}(z)) d\alpha(z), \quad (22)$$

where $\varphi_{(x,y)}$ is the associated conjugating homeomorphism, such that,

$$\varphi_{(x,y)} : (\overline{|x_1^0, x_2^0, \dots, x_s^0}) \rightarrow \overline{|y_1^0, y_2^0, \dots, y_s^0}$$

Example 12. Consider the homeomorphism $\varphi : \overline{|112|2} \rightarrow \overline{|1122}$ given by

$$\varphi(\dots z_{-4} 112|2 z_2 z_3 z_4 \dots) = (\dots z_{-4} z_2 z_3 z_4 |1122 z_5 \dots).$$

Note that $\overline{|112|2}$ is translation by τ^{-3} of the set $\overline{|1122}$.

Consider the conjugating homeomorphisms, $\varphi_1, \varphi_2, \varphi_3$ and φ_4 , given by

$$\varphi_1(\dots z_{-4} 112|2 \mathbf{11} z_4 \dots) = (\dots z_{-4} \mathbf{11} |1122 z_5 \dots),$$

$$\varphi_2(\dots z_{-4} 112|2 \mathbf{12} z_4 \dots) = (\dots z_{-4} \mathbf{12} |1122 z_5 \dots),$$

$$\varphi_3(\dots z_{-4} 112|2 \mathbf{21} z_4 \dots) = (\dots z_{-4} \mathbf{21} |1122 z_5 \dots),$$

$$\varphi_4(\dots z_{-4} 112|2 \mathbf{22} z_4 \dots) = (\dots z_{-4} \mathbf{22} |1122 z_5 \dots).$$

Suppose α is quasi- C^* Gibbs and satisfies (21).

Therefore,

$$\begin{aligned} & \int_{\overline{|112|2}} e^{V(x, \varphi(x))} f(\varphi(x)) d\alpha(x) = \\ & \int_{\overline{|112|211}} e^{V(x, \varphi(x))} f(\varphi(x)) + \int_{\overline{|112|212}} e^{V(x, \varphi(x))} f(\varphi(x)) + \\ & \int_{\overline{|112|221}} e^{V(x, \varphi(x))} f(\varphi(x)) + \int_{\overline{|112|222}} e^{V(x, \varphi(x))} f(\varphi(x)) = \\ & \int_{\overline{|112|211}} e^{V(x, \varphi_1(x))} f(\varphi_1(x)) + \int_{\overline{|112|212}} e^{V(x, \varphi_2(x))} f(\varphi_2(x)) + \end{aligned}$$

$$\begin{aligned} & \int_{\overline{112|221}} e^{V(x,\varphi_3(x))} f(\varphi_3(x)) + \int_{\overline{112|222}} e^{V(x,\varphi_4(x))} f(\varphi_4(x)) \leq \\ & \frac{1}{d_1} \left[\int_{\overline{11|1122}} f(x) + \int_{\overline{12|1122}} f(x) + \int_{\overline{21|1122}} f(x) + \int_{\overline{22|1122}} f(x) \right] = \\ & \frac{1}{d_1} \int_{\overline{1122}} f d\alpha(x), \end{aligned}$$

where some of the $d\alpha$ were omitted. We proved that

$$\int_{\overline{112|2}} e^{V(x,\varphi(x))} f(\varphi(x)) d\alpha(x) \leq \frac{1}{d_1} \int_{\overline{1122}} f d\alpha(x),$$

for any measurable function f .

Taking $f = 1$, we get that

$$\int_{\overline{112|2}} e^{V(x,\varphi(x))} d\alpha(x) \leq \frac{1}{d_1} \int_{\overline{1122}} d\alpha(x).$$

As $e^{V(x,\varphi(x))}$ is strictly positive we get that if $\alpha(\overline{1122}) = 0$, then, $\alpha(\overline{112|2}) = 0$.

Using the inequality for d_2 in (21) we get in a similar way that if $\alpha(\overline{112|2}) = 0$, then, $\alpha(\overline{1122}) = 0$.

One can also show that

$$\int_{\overline{1122}} d\alpha(x) \leq d_2 \int_{\overline{112|2}} e^{V(x,\varphi(x))} d\alpha(x).$$

Proposition 13. Suppose α is quasi- C^* -Gibbs for a **potential** U that depends on finite coordinates, then

$$\alpha(\overline{a_{-r}\dots a_{-1}|a_1 a_2 \dots a_s}) > 0,$$

if and only if,

$$\alpha(\overline{|\overline{a_{-r}\dots a_{-1} a_1 a_2 \dots a_s}}) > 0.$$

Moreover, there exist $b_1 > 0, b_2 > 0$, such that, for any cylinder set of the form $\overline{a_{-r}\dots a_{-1}|a_1 a_2 \dots a_s}$ we get

$$\begin{aligned} b_1 \alpha(\overline{a_{-r}\dots a_{-1}|a_1 a_2 \dots a_s}) &\leq \alpha(\overline{|\overline{a_{-r}\dots a_{-1} a_1 a_2 \dots a_s}}) \leq \\ &b_2 \alpha(\overline{a_{-r}\dots a_{-1}|a_1 a_2 \dots a_s}). \end{aligned} \tag{23}$$

Proof: We left the proof for the reader which is an adaptation of the reasoning of Example 12. □

The next result shows that we can always consider normalized potentials (see Theorem 2.2 in [16] for general results) on the definition of quasi C^* -Gibbs probability.

Theorem 14. *Suppose the probability α on Ω is C^* -Gibbs for Hölder potential U . Assume, $X : \Omega \rightarrow \mathbb{R}$ is such that $X = U + g - g \circ \tau + \lambda$, where $g : \Omega \rightarrow \mathbb{R}$ is a Hölder continuous function and λ a constant, then α is quasi C^* -Gibbs for X .*

Proof: Suppose that for any continuous f we have

$$\int_{O_{x,y}} e^{\beta \sum_{k=-\infty}^{\infty} U(\tau^k(\varphi(z))) - U(\tau^k(z))} f(\varphi(z)) d\alpha(z) = \int_{\varphi(O_{x,y})} f(z) d\alpha(z) \quad (24)$$

Note that

$$\sum_{k=-\infty}^{\infty} [g(\tau^k(z)) - g(\tau^k(\varphi(z)))]$$

is limited since g is Hölder, actually the summation is absolutely convergent by the same reason. The same can be said of

$$\sum_{k=-\infty}^{\infty} [g(\tau^{k+1}(z)) - g(\tau^{k+1}(\varphi(z)))]$$

and of

$$\sum_{k=-\infty}^{\infty} [U(\tau^k(z)) - U(\tau^k\varphi(z))]$$

The absolute convergence allow us to sum the quantities above in any order, the resulting sum is limited since each of the above quantities are.

Therefore,

$$\begin{aligned} & \sum_{k=-\infty}^{\infty} [X(\tau^k(\varphi(z))) - X(\tau^k(z))] = \\ & [\sum_{k=-\infty}^{\infty} U(\tau^k(\varphi(z))) - U(\tau^k(z))] + \end{aligned}$$

$$\begin{aligned} & \left[\sum_{k=-\infty}^{\infty} g(\tau^k(\varphi(z))) - g(\tau^k(z)) \right] - \\ & \left[\sum_{k=-\infty}^{\infty} g(\tau^{k+1}(\varphi(z))) - g(\tau^{k+1}(z)) \right] \end{aligned}$$

is bounded above and below by constants which do not depend on $x \sim y$, $O_{x,y}$ and corresponding $\varphi_{x,y}$.

Then, α is quasi C^* -Gibbs for X . □

By Proposition 1.2 in [16] given a Hölder potential $U : \Omega \rightarrow \mathbb{R}$, one can find W depending on positive coordinates $(1, 2, 3, \dots, n, \dots) \in \{1, 2, \dots, d\}^{\mathbb{N}}$ and a continuous function $v : \Omega \rightarrow \mathbb{R}$ (which depends on finite coordinates), such that, $W = U + v - v \circ \tau$.

The function V is Hölder and then last theorem can be applied.

More precisely, there exist $\tilde{W} : \{1, 2, \dots, d\}^{\mathbb{N}} \rightarrow \mathbb{R}$ an r , such that,

$$\begin{aligned} W(\dots x_{-n-1} \ x_{-n} x_{-n+1} \dots x_{-1} \mid x_1 \dots x_m \ x_{m+1} \dots) = \\ \tilde{W}(x_1 \dots x_m \ x_{m+1} \dots) = K(x_1 \dots x_r), \end{aligned}$$

for a certain function $K : \{1, 2, \dots, d\}^r \rightarrow \mathbb{R}$.

The bottom line is: from Theorem 2.2 in [16], given such \tilde{W} one can find, u and positive constant λ , such that, $\tilde{W} = \tilde{U} + u - u \circ \tau + \lambda$. Moreover, $\tilde{U} : \{1, 2, \dots, d\}^{\mathbb{N}} \rightarrow \mathbb{R}$ and $u : \{1, 2, \dots, d\}^{\mathbb{N}} \rightarrow \mathbb{R}$ both depend on a finite number of coordinates.

Remark 2: Therefore, from Theorem 14 if α is C^* -Gibbs for a Hölder potential $U : \Omega \rightarrow \mathbb{R}$, which depends on a finite number of coordinates, we can assume that α is quasi- C^* -Gibbs for **another** potential, denoted \tilde{U} , which is normalized and depending on a finite number of coordinates.

By abuse of language one can write $\tilde{U} : \{1, 2, \dots, d\}^{\mathbb{Z}} \rightarrow \mathbb{R}$.

5 Equivalence between equilibrium measures and C^* -Gibbs measures

First we present two important and well known theorems (see theorems 1.2 and 1.22 in [3] and also [21]).

We will consider without loss of generality that $\beta = 1$.

$\mathcal{M}_\tau(\Omega)$ denotes the set on invariant probabilities for τ acting on Ω .

Theorem 15. (see Theorem 1.2 in [3]) Suppose $U : \Omega \rightarrow \mathbb{R}$ is of Hölder class. Then, there is a unique $\rho \in \mathcal{M}_\tau(\Omega)$, for which one can find constants $C_1 > 0$, $C_2 > 0$, and P such that, **for all** $s \geq 0$, for all cylinder $\overline{|y_1^0, y_2^0, \dots, y_s^0}$ we have

$$C_1 \leq \frac{\rho(\overline{|y_1^0, y_2^0, \dots, y_s^0})}{\exp(-P s + \sum_{k=0}^{s-1} U(\tau^k x))} \leq C_2, \quad (25)$$

where

$$x = (\dots x_{-k}, x_{-k+1}, \dots, x_{-1} \mid x_1, \dots, x_m, x_{m+1}, \dots) \in \overline{|y_1^0, y_2^0, \dots, y_s^0} \subset \Omega,$$

We call (25) the Bowen's inequalities.

Definition 16. The probability $\rho = \rho_U$ of Theorem 15 is called **equilibrium probability** for the potential U .

Theorem 17. Given U as above and ρ_U the equilibrium measure for U , then ρ_U is the unique probability on $\mathcal{M}_\tau(\Omega)$, for which

$$h(\rho_U) + \int U d\rho_U = P(U) := \sup_{\nu \in \mathcal{M}_\tau} \{h(\nu) + \int U d\nu\},$$

where $h(\nu)$ is the entropy of ν .

For a proof see [16] or [3].

$P(U)$ is called the pressure of U . One can show that the P of (25) is equal to such $P(U)$.

Remember that if α is C^* -Gibbs for V , and $V(z, \varphi(z)) = \sum_{k=-\infty}^{+\infty} U(z) - U(\varphi(z))$ we also say by abuse of language that α is C^* -Gibbs for $U : \Omega \rightarrow \mathbb{R}$.

Note that if ρ is an equilibrium probability for a Hölder potential U , then, it is also an equilibrium probability for $U + (g \circ \tau) - g + c$, where c is constant and $g : \Omega \rightarrow \mathbb{R}$ is Hölder continuous (see [16]). In this way we can assume without lost of generality that ρ_U is an equilibrium probability for a normalized potential U . If U is normalized then $P(U) = 0$.

If α on Ω is C^* -Gibbs for U , then, from Remark 2 we have that α is quasi- C^* -Gibbs for **another** potential U which is normalized.

Note that given U we are dealing with two definitions: C^* -Gibbs and Equilibrium. From the above comments we can assume in either case that U is normalized.

The bottom line is: we can assume (see [16]) that the Hölder potential $\tilde{U} = U + (g \circ \tau) - g + c$ is normalized, depends just on future coordinates $\tilde{U} : \{1, 2, \dots, d\}^{\mathbb{N}} \rightarrow \mathbb{R}$ and has pressure zero.

We will work here (due to Theorem 14 and the above comments) with the case where the probability α - which is C^* -Gibbs for the potential U - is also a quasi- C^* -Gibbs probability for the potential \tilde{U} satisfying Pressure $P(\tilde{U}) = 0$. In this case, if we want to prove expression (25) for such probability α over Ω , this can be simplified just showing that there exist $c_1, c_2 > 0$, such that,

$$c_1 \leq \frac{\alpha(\overline{|y_1^0, y_2^0, \dots, y_s^0})}{\exp\left(\sum_{k=0}^{s-1} \tilde{U}(\sigma^k x)\right)} \leq c_2, \quad (26)$$

where σ is the shift acting on $\{1, 2, \dots, d\}^{\mathbb{N}}$ and where x is of the form

$$x = (y_1^0, y_2^0, \dots, y_s^0, x_{s+1}, \dots, x_m, x_{m+1}, \dots) \in \{1, 2, \dots, d\}^{\mathbb{N}}.$$

Remark 3: Indeed, due to Remark 2 we get that $\tilde{U} = U + (g \circ \tau) - g + c$, where g depends on finite coordinates. Therefore, to show (26) - for α **which is C^* -Gibbs for $U : \Omega \rightarrow \mathbb{R}$** - is equivalent to prove (see details on the proof of Theorem 14) that there exists $C_1, C_2 > 0$, such that,

$$C_1 \leq \frac{\alpha(\overline{|y_1^0, y_2^0, \dots, y_s^0})}{\exp\left(\sum_{k=0}^{s-1} U(\tau^k x)\right)} \leq C_2, \quad (27)$$

where τ is the shift acting on $\{1, 2, \dots, d\}^{\mathbb{Z}}$ and where

$$x = (\dots x_{-2}, x_{-1} | y_1^0, y_2^0, \dots, y_s^0, x_{s+1}, \dots, x_m, x_{m+1}, \dots) \in \{1, 2, \dots, d\}^{\mathbb{Z}}.$$

It's important to note that the main equivalence (equilibrium and C^* -Gibbs) is still valid in a more general setting of a Hölder potential in a general Smale Space. D. Ruelle proved on the setting of hyperbolic diffeomorphisms that Equilibrium implies C^* -Gibbs in his book [21], see theorems 7.17(b), 7.13(b) and section 7.18). On the other hand Haydn proved in the paper [10] that C^* -Gibbs implies Equilibrium. Later, the paper [11] presents a shorter proof of the equivalence.

On the two next sections we will present the proof of the following theorem.

Theorem 18. *Given a potential U depending on a finite number of coordinates, then, α is the equilibrium measure for U , if and only if, α is C^* -Gibbs for U . As the equilibrium probability is unique we get that the C^* -Gibbs probability for U is unique.*

6 Equilibrium implies C^* -Gibbs

The fact that Equilibrium state implies C^* -Gibbs was proved by Ruelle in a general setting. The proof is in the book [21] (see theorems 7.17(b), 7.13(b) and section 7.18).

For completeness we will explain the proof on our setting.

We drop the (x, y) on $\varphi_{(x,y)}$ and $\mathcal{O}_{(x,y)}$.

Lemma 19. *Let (Ω, τ) be the shift on the Bernoulli space $\Omega = \{1, 2, \dots, d\}^{\mathbb{Z}-\{0\}}$ and ρ_0 be the τ -invariant probability measure which realizes the maximum of the entropy, or, simply the equilibrium state for $U = 0$. If (\mathcal{O}, φ) is a conjugating homeomorphism, then for any continuous function f*

$$\int_{\mathcal{O}} f(\varphi(x)) d\rho_0(x) = \int_{\varphi(\mathcal{O})} f(x) d\rho_0(x) \quad (28)$$

Proof: Given

$$\mathcal{O} = \overline{x_{-n}x_{-n+1}\dots x_{-1} \mid x_1 \dots x_{m-1}x_m}$$

and

$$\varphi(\mathcal{O}) = \overline{y_{-n}y_{-n+1}\dots y_{-1} \mid y_1 \dots y_{m-1}y_m},$$

we have that for any $r > m$ and $k > n$

$$\begin{aligned} \rho_0(\overline{x_{-k}x_{-k+1}\dots x_{-1} \mid x_1 \dots x_{r-1}x_r}) &= d^{-(r+k)} = \\ &= \rho_0(\overline{y_{-k}y_{-k+1}\dots y_{-1} \mid y_1 \dots y_{r-1}y_r}). \end{aligned} \quad (29)$$

We shall prove that equation (28) is valid when f is equal to an characteristic function of an arbitrary cylinder. Note that for this purpose is enough to consider f as the characteristic function of cylinders of the form $\overline{y_{-k}y_{-k+1}\dots y_{-1} \mid y_1 \dots y_{r-1}y_r}$. Therefore,

$$\begin{aligned} \int_{\mathcal{O}} I_{\overline{y_{-k}y_{-k+1}\dots y_{-1} \mid y_1 \dots y_{r-1}y_r}}(\varphi(x)) d\rho_0(x) &= \\ \int_{\varphi(\mathcal{O})} I_{\overline{y_{-k}y_{-k+1}\dots y_{-1} \mid y_1 \dots y_{r-1}y_r}}(y) d\rho_0(y). \end{aligned}$$

From this follows the claim.

The main issue on the above proof is property (29). □

We denote by $C^\alpha(\Omega)$ the set of α Hölder functions on Ω .

Lemma 20. (see corollary 7.13 in [21]) Consider the shift space (Ω, τ) and $A, B \in C^\alpha(\Omega)$. Write for integers $a < 0$ and $b > 0$

$$Z_{[a,b]} = \int e^{\sum_{k=a}^{b-1} B \circ \tau^k} d\rho_A$$

Then, $Z_{[a,b]}^{-1} (\exp \sum_{k=a}^{b-1} B \circ \tau^k) \rho_A$ tends to ρ_{A+B} in the weak star topology, when $a \rightarrow -\infty$ and $b \rightarrow +\infty$.

In particular, taking $A = 0$, when $a \rightarrow -\infty$ and $b \rightarrow +\infty$, we get that

$$Z_{[a,b]}^{-1} e^{\sum_{k=a}^{b-1} B \circ \tau^k} \rho_0 \rightarrow \rho_B,$$

where

$$Z_{[a,b]} = \int e^{\sum_{k=a}^{b-1} B \circ \tau^k} d\rho_0$$

Theorem 21. If ρ_B is an equilibrium state for a potential B that depends on a finite number of coordinates then it is a C^* -Gibbs state for B .

Proof: The statement holds for $B = 0$ by Lemma 19. Moreover, Lemma 20 allow us to extend this result for all $B \in C^\alpha(\Sigma_N)$ in the following manner: given \mathcal{O} and the associated φ

$$\begin{aligned} \int_{\varphi(\mathcal{O})} g(x) d\rho_B(x) &= \lim_{\substack{a \rightarrow -\infty \\ b \rightarrow \infty}} Z_{[a,b]}^{-1} \int_{\varphi(\mathcal{O})} \exp\left(\sum_{k=a}^{b-1} B \circ \tau^k(x)\right) g(x) d\rho_0(x) \stackrel{19}{=} \\ &= \lim_{\substack{a \rightarrow -\infty \\ b \rightarrow \infty}} Z_{[a,b]}^{-1} \int_{\mathcal{O}} \exp\left(\sum_{k=a}^{b-1} B \circ \tau^k \circ \varphi(x)\right) g \circ \varphi(x) d\rho_0(x) = \\ &= \lim_{\substack{a \rightarrow -\infty \\ b \rightarrow \infty}} Z_{[a,b]}^{-1} \int_{\mathcal{O}} \exp\left(\sum_{k=a}^{b-1} B \circ \tau^k \circ \varphi(x) - \sum_{k=0}^{b-1} B \circ \tau^k(x)\right) \\ &\quad \exp\left(\sum_{k=a}^{b-1} B \circ \tau^k(x)\right) g \circ \varphi(x) d\rho_0(x) = \\ &= \lim_{\substack{a \rightarrow -\infty \\ b \rightarrow \infty}} Z_{[a,b]}^{-1} \int_{\mathcal{O}} e^{(-V(x, \varphi(x)))} g \circ \varphi(x) \exp\left(\sum_{k=a}^{b-1} B \circ \tau^k(x)\right) d\rho_0(x) = \\ &\quad \int_{\mathcal{O}} e^{(-V(x, \varphi(x)))} g \circ \varphi(x) d\rho_B(x). \end{aligned}$$

Since the equality

$$\int_{\varphi(\mathcal{O})} g(x) d\rho_B(x) = \int_{\mathcal{O}} e^{(-V(x, \varphi(x)))} g \circ \varphi(x) d\rho_B(x)$$

was verified for any conjugating homeomorphism φ and any g , then it follows that ρ_B is an C^* -Gibbs state for B . □

7 C^* -Gibbs implies Equilibrium

Given a C^* -Gibbs probability α for a potential U that depends on a finite number of coordinates we will show in this section that α is the equilibrium probability for U . We shall further assume that the potential U depend only on positive coordinates and is normalized according to the Ruelle operator, i.e.

$$\sum_{z_1, z_2, \dots, z_n=1}^d e^{\sum_{j=0}^{n-1} \tilde{U}(\sigma^j(z_1, z_2, \dots, z_n, w_1, w_2, w_3, \dots, w_m, \dots))} = 1, \quad (30)$$

for any $w = (w_1, w_2, \dots, w_m, \dots) \in \{1, 2, \dots, d\}^{\mathbb{N}}$ and $n \in \mathbb{N}$. Such assumptions aren't restrictive, since given any potential W that depends on a finite number of coordinates, it's possible to find a function g depending on finite coordinates, and a normalized potential \tilde{W} that depends of future coordinates, such that [16]

$$W = \tilde{W} + g - g \circ \tau - \lambda$$

If we show that α is τ -invariant and also satisfies the Bowen's inequalities for U , then, it will follow that α is the equilibrium probability for U by Theorem 15.

We will show first that a quasi C^* -Gibbs probability α for U satisfies the Bowen's inequalities (27) for U .

Later we will show that a C^* -Gibbs probability α is invariant for τ (see Proposition 26). This will finally show (see Theorem 27) that " C^* -Gibbs implies Equilibrium".

Note that we want to show (27) but due to Remark 3 we just have to show (26).

We assume α is such that (22) is true, that is, there exists $d_1, d_2 > 0$, such that, for any continuous function g

$$\begin{aligned} d_1 \int_{|x_1^0, x_2^0, \dots, x_s^0} e^{-V(z, \varphi_{(x,y)}(z))} g(\varphi_{(x,y)}(z)) d\alpha(z) &\leq \\ \int_{|y_1^0, y_2^0, \dots, y_s^0} g(z) d\alpha(z) &\leq d_2 \int_{|x_1^0, x_2^0, \dots, x_s^0} e^{-V(z, \varphi_{(x,y)}(z))} g(\varphi_{(x,y)}(z)) d\alpha(z). \end{aligned} \quad (31)$$

We denote $\mathcal{U} = \sup_{x \in \Omega} U(x) - \inf_{x \in \Omega} U(x)$.

Lemma 22. *Given a normalized Hölder potential $U(x) = f(x_1, x_2, \dots, x_r)$, consider $x_1^0 \dots x_s^0$ and $y_1^0 \dots y_s^0$ fixed, and also $a, b \in \{1, 2, \dots, d\}$ fixed. Let*

$$x = (\dots x_{-m} x_{-m+1} \dots x_{-1} \mid x_1^0 \dots x_s^0 x_{s+1}, x_{s+2}, \dots x_{m-1} x_m \dots) \in \overline{|x_1^0, x_2^0, \dots x_s^0}$$

$$y = (\dots x_{-m} x_{-m+1} \dots x_{-1} \mid y_1^0 \dots y_s^0 x_{s+1}, x_{s+2}, \dots x_{m-1} x_m \dots) \in \overline{|y_1^0, y_2^0, \dots y_s^0,$$

and also

$$x_a = (\dots x_{-m} x_{-m+1} \dots x_{-1} \mid x_1^0 \dots x_s^0 \mathbf{a} x_{s+2} \dots x_{m-1} x_m \dots) \in \overline{|x_1^0, x_2^0, \dots x_s^0}$$

$$y_b = (\dots x_{-m} x_{-m+1} \dots x_{-1} \mid y_1^0 \dots y_s^0 \mathbf{b} x_{s+2} \dots x_{m-1} x_m \dots) \in \overline{|y_1^0, y_2^0, \dots y_s^0.$$

Assume that $x \sim y$.

Then,

$$\begin{aligned} & \left| \sum_{k=-\infty}^{\infty} U(\tau^k(x_a)) - U(\tau^k(y_b)) \right| \leq \\ & 2r\mathcal{U} + \left| \sum_{k=-\infty}^{\infty} U(\tau^k(x)) - U(\tau^k(y)) \right|. \end{aligned}$$

Proof: Let \mathbb{I} the set of indicies for k such that $U(\tau^k(x_a))$ (or, $U(\tau^k(y_b))$) differs from $U(\tau^k(x))$ (or, $U(\tau^k(y))$). It's easy to see that the cardinality of \mathbb{I} is r . Therefore

$$\begin{aligned} & \left| \sum_{k \in \mathbb{Z}} U(\tau^k(x_a)) - U(\tau^k(y_b)) \right| \leq \\ & \left| \sum_{k \in \mathbb{Z} \setminus \mathbb{I}} U(\tau^k(x_a)) - U(\tau^k(y_b)) \right| + \left| \sum_{k \in \mathbb{I}} U(\tau^k(x_a)) - U(\tau^k(y_b)) \right| = \\ & \left| \sum_{k \in \mathbb{Z} \setminus \mathbb{I}} U(\tau^k(x)) - U(\tau^k(y)) \right| + \left| \sum_{k \in \mathbb{I}} U(\tau^k(x_a)) - U(\tau^k(y_b)) \right| \leq \\ & \left| \sum_{k \in \mathbb{Z} \setminus \mathbb{I}} U(\tau^k(x)) - U(\tau^k(y)) \right| + r\mathcal{U} \leq \end{aligned}$$

$$\left| \sum_{k \in \mathbb{Z}} U(\tau^k(x)) - U(\tau^k(y)) \right| + 2r\mathcal{U}$$

□

We will adapt the formulation of Proposition 2.1 in [10] to the present situation.

For fixed $\overline{|x_1^0, x_2^0, \dots, x_s^0|}$ denote

$$U_a = \overline{|x_1^0, x_2^0, \dots, x_s^0, a|}$$

$a = 1, 2, \dots, d$.

Note that $\sum_a \alpha(U_a) = \alpha(\overline{|x_1^0, x_2^0, \dots, x_s^0|})$, in particular

$$\sum_a \alpha(U_a) < d \alpha(\overline{|x_1^0, x_2^0, \dots, x_s^0|}). \quad (32)$$

Consider now a fixed $\overline{|y_1^0, y_2^0, \dots, y_s^0|}$ and $\varphi_{a,b}$, $a = 1, 2, \dots, d$, $b = 1, 2, \dots, d$, denotes the conjugating homeomorphism from U_a to $\overline{|y_1^0, y_2^0, \dots, y_s^0|} \circ \varphi_{a,b} = \varphi_{a,b}(U_a)$.

Note also that for each a

$$\alpha(\overline{|y_1^0, y_2^0, \dots, y_s^0|}) = \sum_{b=1}^d \alpha(\varphi_{a,b}(U_a)). \quad (33)$$

Denote

$$K = \sup_{m \in \mathbb{N}} \left\{ \sum_{k=0}^{m-1} [\tilde{U}\tau^k(u) - \tilde{U}\tau^k(v)] \right\}, \text{ where } u, v \in \overline{|a_1, a_2, \dots, a_m|},$$

$$\text{and } (a_1, a_2, \dots, a_m) \in \{1, 2, \dots, d\}^m \}.$$

On the above expression we ask that $u \sim v$.

Note that if α is C^* -Gibbs and satisfies (31) we get in particular that

$$d_1 \int_{\overline{|x_1^0, x_2^0, \dots, x_s^0|}} e^{-V(z, \varphi_{(x,y)}(z))} d\alpha(z) \leq \int_{\overline{|y_1^0, y_2^0, \dots, y_s^0|}} d\alpha(z) \leq d_2 \int_{\overline{|x_1^0, x_2^0, \dots, x_s^0|}} e^{-V(z, \varphi_{(x,y)}(z))} d\alpha(z). \quad (34)$$

Proposition 23. *Suppose α is quasi- C^* -Gibbs for U as above. Then, there exists a constant $c_1 > 0$, such that,*

$$c_1 \leq e^{-\sum_{k=0}^{s-1} U\tau^k(x)} \alpha(\overline{|x_1^0, x_2^0, \dots, x_s^0|})$$

for any cylinder $\overline{|x_1^0, x_2^0, \dots, x_s^0|}$ and any x on the cylinder.

The α -probability of any cylinder is positive.

Proof: We assume that (34) is true.

Fix a certain cylinder $\overline{|x_1^0, x_2^0, \dots, x_s^0|}$ and fix a point $x \in \overline{|x_1^0, x_2^0, \dots, x_s^0|}$ then choose another cylinder $\overline{|y_1^0, y_2^0, \dots, y_s^0|}$ with non null probability and a point $y \in \overline{|y_1^0, y_2^0, \dots, y_s^0|}$. Fix $x \in \overline{|x_1^0, x_2^0, \dots, x_s^0|}$ and $y \in \overline{|y_1^0, y_2^0, \dots, y_s^0|}$. Choose $a, b \in \{1, 2, \dots, d\}$ and define x_a and y_b as

$$x_a = (\dots x_{-m} x_{-m+1} \dots x_{-1} | x_1^0 \dots x_s^0 \mathbf{a}, x_{s+2}, \dots, x_{m-1} x_m \dots) \in \overline{|x_1^0, x_2^0, \dots, x_s^0|}$$

$$y_b = (\dots x_{-m} x_{-m+1} \dots x_{-1} | y_1^0 \dots y_s^0 \mathbf{b}, x_{s+2}, \dots, x_{m-1} x_m \dots) \in \overline{|y_1^0, y_2^0, \dots, y_s^0|}.$$

we get from Lemma 22 that

$$\begin{aligned} \alpha(\varphi_{a,b}(U_a)) &\leq d_2 \int_{U_a} e^{\sum_{k=-\infty}^{\infty} U(\tau^k \varphi(z)) - U(\tau^k(z))} d\alpha(z) \leq \\ d_2 \int e^{\sum_{k=0}^s U(\tau^k \varphi(z)) - U(\tau^k y_b) + U(\tau^k \varphi(z)) - U(\tau^k x_a)} e^{\sum_{k=0}^s U(\tau^k y_b) - U(\tau^k x_a)} \\ e^{\sum_{k=s}^{\infty} U(\tau^k \varphi(z)) - U(\tau^k z)} e^{\sum_{k=0}^{\infty} U(\tau^{-k} \varphi(z)) - U(\tau^{-k} z)} d\alpha(z) &\leq \\ d_2 e^{2K+r\mathcal{U}} e^{\sum_{k=0}^{s-1} [\tilde{U}\tau^k(y_b) - \tilde{U}\tau^k(x_a)]} \alpha(U_a) &\leq \\ d_2 e^{2K+3r\mathcal{U}} e^{\sum_{k=0}^{s-1} [\tilde{U}\tau^k(y) - \tilde{U}\tau^k(x)]} \alpha(U_a). \end{aligned}$$

Then, from (33)

$$\alpha(\overline{|y_1^0, y_2^0, \dots, y_s^0|}) = \sum_{b=1}^d \alpha(\varphi_{a,b}(U_a)) \leq d_2 d e^{2K+3r\mathcal{U}} e^{\sum_{k=0}^{s-1} [U\tau^k(y) - U\tau^k(x)]} \alpha(U_a).$$

From this and from (30) we get

$$1 = \sum_{y_1^0, y_2^0, \dots, y_s^0=1}^d \alpha(\overline{|y_1^0, y_2^0, \dots, y_s^0|}) \leq d_2 d e^{2K+3r\mathcal{U}} e^{-\sum_{k=0}^{s-1} U\tau^k(x)} \alpha(U_a),$$

and, finally, for $x = (\dots, x_{-t}, \dots, x_{-2}, x_{-1} | x_1, x_2, \dots, x_t, \dots) \in \overline{|x_1^0, x_2^0, \dots, x_s^0|}$

$$d = \sum_{a=1}^d \sum_{y_1^0, y_2^0, \dots, y_s^0=1}^d \alpha(\overline{|y_1^0, y_2^0, \dots, y_s^0|}) \leq \sum_{a=1}^d d_2 d e^{2K+3r\mathcal{U}} e^{-\sum_{k=0}^{s-1} U\tau^k(x)} \alpha(U_a) =$$

$$d_2 d e^{2K+3r\mathcal{U}} e^{-\sum_{k=0}^{s-1} U\tau^k(x)} \alpha(\overline{|x_1^0, x_2^0, \dots, x_s^0}).$$

This also shows that the α -probability of any cylinder $\overline{|x_1^0, x_2^0, \dots, x_s^0}$ is positive when α is quasi- C^* -Gibbs.

By Proposition 13 we get that any cylinder of the form $\overline{x_{-m}\dots x_{-1}|x_1x_2\dots x_s}$ has positive α -probability. □

Proposition 24. *There exists a constant $c_2 > 0$, such that,*

$$e^{-\sum_{k=0}^{s-1} U\tau^k(x)} \alpha(\overline{|x_1^0, x_2^0, \dots, x_s^0}) \leq c_2,$$

for any cylinder $\overline{|x_1^0, x_2^0, \dots, x_s^0}$ and any x on the cylinder.

The α -probability of any cylinder is positive.

Proof: We assume that (34) is true.

Again consider fixed $x \in \overline{|x_1^0, x_2^0, \dots, x_s^0}$ and $y \in \overline{|y_1^0, y_2^0, \dots, y_s^0}$. Choose $a, b \in \{1, 2, \dots, d\}$ and define x_a and y_b as

$$x_a = (\dots x_{-m} x_{-m+1} \dots x_{-1} | x_1^0 \dots x_s^0 \mathbf{a}, x_{s+2}, \dots, x_{m-1} x_m \dots) \in \overline{|x_1^0, x_2^0, \dots, x_s^0}$$

$$y_b = (\dots x_{-m} x_{-m+1} \dots x_{-1} | y_1^0 \dots y_s^0 \mathbf{b}, x_{s+2}, \dots, x_{m-1} x_m \dots) \in \overline{|y_1^0, y_2^0, \dots, y_s^0}.$$

Using an analogous reasoning as in proposition 24. But now we use the function $g(z) = e^{V(z, \varphi(z))}$ in the first inequality of (31). After some algebraic work similar to the former demonstration we reach

$$\alpha(U_a) \leq \frac{1}{d_1} e^{2K+r\mathcal{U}} e^{\sum_{k=0}^{s-1} [U\tau^k(x_a) - U\tau^k(y_b)]} \alpha(\varphi_{a,b}(U_a)) \leq$$

$$\frac{1}{d_1} e^{2K+3r\mathcal{U}} e^{\sum_{k=0}^{s-1} [U\tau^k(x) - U\tau^k(y)]} \alpha(\varphi_{a,b}(U_a)).$$

Therefore,

$$e^{\sum_{k=0}^{s-1} U\tau^k(y)} \alpha(\overline{|x_1^0, x_2^0, \dots, x_s^0}) = e^{\sum_{k=0}^{s-1} U\tau^k(y)} \sum_{a=1}^d \alpha(U_a) \leq$$

$$\frac{1}{d_1} e^{2K+3r\mathcal{U}} e^{\sum_{k=0}^{s-1} U\tau^k(x)} \sum_{a=1}^d \alpha(\varphi_{a,b}(U_a)). \quad (35)$$

Finally, as $\overline{y_1^0, y_2^0, \dots, y_s^0} b = \varphi_{a,b}(U_a)$ we get from (30) and (35)

$$d \alpha(\overline{x_1^0, x_2^0, \dots, x_s^0}) = \sum_{b=1}^d \sum_{y_1^0, y_2^0, \dots, y_s^0=1}^d e^{\sum_{k=0}^{s-1} U \tau^k(y)} \alpha(\overline{x_1^0, x_2^0, \dots, x_s^0}) \leq$$

$$\frac{e^{2K+3rU}}{d_1} e^{\sum_{k=0}^{s-1} U \tau^k(x)} \sum_{a=1}^d \sum_{b=1}^d \sum_{y_1^0, y_2^0, \dots, y_s^0=1}^d \alpha(\varphi_{a,b}(U_a)) = \frac{d e^{2K+3rU}}{d_1} e^{\sum_{k=0}^{s-1} U \tau^k(x)}.$$

This shows the claim of the proposition. \square

Now we have to show that α is invariant by τ .

Corollary 25. *If α_1 and α_2 are quasi C^* -Gibbs for U , where*

$$U(\dots, x_{-n}, \dots, x_{-2}, x_{-1} \mid x_1, x_2, \dots, x_r, x_{r+1}, \dots, x_m \dots) = f(x_1, x_2, \dots, x_r)$$

for some fixed r and function $f : \{1, 2, \dots, d\}^r \rightarrow \mathbb{R}$, then α_1 is absolutely continuous with respect to α_2 .

Proof: We assume that U is normalized. Suppose α_1 and α_2 are quasi C^* -Gibbs for U .

Expression (26) for α_1 and α_2 will determine, respectively, constants d_1^1, d_2^1 and d_1^2, d_2^2 .

From last Propositions there exist constants $Y_1 > 0$ and $Y_2 > 0$, such that, for any cylinder $\overline{x_1, x_2, \dots, x_n}$ and for any point x in this cylinder we get

$$\frac{\alpha_1(\overline{x_1, x_2, \dots, x_n})}{e^{\sum_{k=0}^{n-1} U(\tau^k(x))}} \leq Y_1,$$

and

$$Y_2 \leq \frac{\alpha_2(\overline{x_1, x_2, \dots, x_n})}{e^{\sum_{k=0}^{n-1} U(\tau^k(x))}}.$$

Therefore,

$$\frac{Y_2}{Y_1} \alpha_1(\overline{x_1, x_2, \dots, x_n}) \leq \alpha_2(\overline{x_1, x_2, \dots, x_n}).$$

Now consider a cylinder set of the form

$$\overline{(x_{-m}, \dots, x_{-1} \mid x_1, x_2, \dots, x_n)}.$$

Expression (23) for α_1 and α_2 will determine, respectively, constants b_1^1, b_2^1 and b_1^2, b_2^2 .

Then, by Proposition 13 we get that

$$b_1^1 \alpha_1(\overline{x_{-m}, \dots, x_{-1} | x_1, x_2, \dots, x_n}) \leq \alpha_1(\overline{x_{-m}, \dots, x_{-1} x_1, x_2, \dots, x_n}) \leq \frac{Y_1}{Y_2} \alpha_2(\overline{x_{-m}, \dots, x_{-1} x_1, x_2, \dots, x_n}) \leq \frac{Y_1}{Y_2} b_2^2 \alpha_2(\overline{x_{-m}, \dots, x_{-1} | x_1, x_2, \dots, x_n}). \quad (36)$$

The Borel sigma-algebra over Ω is generated by the set of cylinders of the form $\overline{x_{-m}, \dots, x_{-1} | x_1, x_2, \dots, x_n}$.

As the probability $\alpha_j(B)$, $j = 1, 2$, of a Borel set B is obtained, respectively, as an exterior probability using probabilities of the generators we finally get that the analogous inequalities as in (36) are true with the same same constants, that is,

$$b_1^1 \alpha_1(B) \leq \frac{Y_1}{Y_2} b_2^2 \alpha_2(B). \quad (37)$$

Therefore, α_1 is absolutely continuous with respect to α_2 . □

Proposition 26. *Assume α is C^* -Gibbs for U , then, α is invariant for τ .*

Proof: From Corollary 25 we get that any two C^* -Gibbs probabilities for U are absolutely continuous with respect to each other.

Suppose α is C^* -Gibbs, then, $\alpha_1 = \tau^*(\alpha)$ is also C^* -Gibbs by Proposition 10. If $\alpha \neq \tau^*(\alpha)$ then, following Theorem 2.5 in [11] we get that $\rho_1 = |\alpha_1 - \alpha| + \alpha_1 - \alpha$ and $\rho_2 = |\alpha_1 - \alpha| - \alpha_1 + \alpha$ are also C^* -Gibbs. But ρ_1 and ρ_2 are singular with respect to each other and this is a contradiction.

Therefore, $\alpha = \tau^*(\alpha)$. □

Theorem 27. *Suppose $U : \Omega \rightarrow \mathbb{R}$ is of the form*

$$U(\dots, x_{-n}, \dots, x_{-2}, x_{-1} | x_1, x_2, \dots, x_r, x_{r+1}, \dots, x_m \dots) = f(x_1, x_2, \dots, x_r),$$

for some fixed r and fixed function $f : \{1, 2, \dots, d\}^r \rightarrow \mathbb{R}$.

If α is C^ -Gibbs for the potential U then α is the equilibrium state for U .*

Proof: As we know by Proposition 26 that α is τ invariant and, moreover, we also know that α is quasi- C^* invariant for another normalized potential, it follows from Proposition 23, Proposition 24 and Theorem 15 that α is the equilibrium probability for U . □

Another conclusion one can get from the above reasoning is that for potentials that depends on finite coordinates the concepts of quasi C^* -Gibbs and C^* -Gibbs are equivalent on the lattice \mathbb{Z} .

8 Construction of the C^* -Algebra

Remember that we consider the groupoid $G \subset \Omega \times \Omega$ of all pair of points which are related by the homoclinic equivalence relation.

Remember also that we consider on G the topology generated by sets of the form

$$\{ (z, \varphi_{(x,y)}(z)) \mid \text{where } z \in \mathcal{O}_{(x,y)} \text{ and } x, y \in \Omega \text{ such that } x \sim y \}.$$

This topology is Hausdorff [20].

We denote by $[x]$ the class of $x \in \Omega$. For each x the set of elements on the class $[x]$ is countable.

We now come to the construction of the noncommutative algebra. Let $\mathcal{C}_c(G)$ be the linear space of complex continuous functions with compact support on G . If $A, B \in \mathcal{C}_c(G)$ we define the product $A * B$ by

$$(A * B)(x, y) = \sum_{z \in [x]} A(x, z)B(z, y).$$

Note that if $(x, y) \in G$ then they are conjugated and so the sum is over all z that are conjugated to x and y .

Note that there are only finitely many nonzero terms in the above sum because the functions A, B have compact support [20].

Considering the above, $A * B \in \mathcal{C}_c(G)$ as one checks readily, so that $\mathcal{C}_c(G)$ becomes an associative complex algebra. An **involution** $A \rightarrow A^*$ is defined by

$$A^*(x, y) = \overline{A(y, x)}$$

where the bar denotes complex conjugation.

For each equivalence class $[x]$ of conjugated points of Ω there is a representation $\pi_{[x]} \rightarrow \mathbb{C}$ in the Hilbert space $l^2([x])$ of square summable functions $[x] \rightarrow \mathbb{C}$, such that

$$((\pi_{[x]}A)\xi)(y) = \sum_{z \in [x]} A(y, z)\xi(z)$$

for $\xi \in l^2([x])$. Denoting by $\|\pi_{[x]}A\|$ the operator norm, we write

$$\|A\| = \sup_{[x]} \|\pi_{[x]}A\|. \quad (38)$$

I_D (the indicator function of the diagonal D) is such that for any $A \in \mathcal{C}_c(G)$ we get $I_D * A = A * I_D = A$.

The completion of $\mathcal{C}_c(G)$ with respect to this norm is separable. It is called the reduced C^* -algebra which is denoted by $C_r^*(G)$. The unity element I_D is contained in this C^* algebra.

Remark 28. If $A \in \mathcal{C}_c(G)$ and $t \in \mathbb{R}$, we write

$$(\sigma^t A)(x, y) = e^{iV(x, y)t} A(x, y) \quad (39)$$

defining a one-parameter group (σ^t) of $*$ -automorphisms of $\mathcal{C}_c(G)$ and a unique extension to a one parameter group of $*$ -automorphisms of $C_r^*(G)$.

We say that $A \in \mathcal{C}_c(G)$ is analytic (a classical terminology on C^* -algebras) if the real variable t on the function $t \rightarrow \sigma^t A$ can be extended to the complex variable $z \in \mathbb{C}$. Under our assumptions this will be always the case. Therefore, $\sigma^{-\beta i} A$ is well defined.

Definition 29. A state ω on $C_r^*(G)$ is a linear functional $\omega : C_r^*(G) \rightarrow \mathbb{C}$, such that, $\omega(A * A^*) \geq 0$, and $\omega(I_D) = 1$ (see [4]).

Such state ω is sometimes called a dynamical C^* -state.

Definition 30. A state ω is invariant if $\omega \circ \sigma^t = \omega$, for all $t \in \mathbb{R}$.

It is of paramount importance to be able to substitute the above real value t by the complex number βi (where β is real). We refer the reader to Propositions 5.3.6 e 5.3.7 in [4] for the technical details of this claim.

Definition 31. Given a modular function $V : G \rightarrow \mathbb{R}$ and the associated σ_t , $t \in \mathbb{R}$, we say that an invariant state $\omega : C_r^*(G) \rightarrow \mathbb{C}$ satisfies the **KMS boundary condition** for V and $\beta \in \mathbb{R}$, if for all $A, B \in C_r^*(G)$, there is a continuous function F on $\{z \in \mathbb{C} : 0 \leq \text{Im}(z) \leq \beta\}$, holomorphic in $\{z \in \mathbb{C} : 0 < \text{Im}(z) < \beta\}$, and such that for any real t

$$\omega(\sigma^t A * B) = F(t), \quad \omega(B * \sigma^t A) = F(t + i\beta) \quad (40)$$

□

Note that using (40) we have that $F(0) = \omega(A \cdot B)$ and

$$F(0) = F(-\beta i + \beta i) = \omega(B * \sigma^{-\beta i} A).$$

Therefore, for any A, B we get

$$\omega(A * B) = \omega(B * e^{-i\beta} A)$$

which is the classical KMS condition for ω according to [4] (see Propositions 5.3.6 e 5.3.7 there). This condition is equivalent to **KMS boundary condition**.

Theorem 32. *If μ is a probability measure on Ω then a state $w = \hat{\mu}$ on $C_r^*(G)$ can be defined for any $A \in \mathcal{C}_c(G)$ by*

$$\hat{\mu}(A) = \int A(x, x) d\mu(x) \quad (41)$$

Proof:

$\hat{\mu}$ is bounded with respect to the above defined norm.

First note that it's easy to verify that $\hat{\mu}$ is linear, and for any A we have $\hat{\mu}(A * A^*) \geq 0$ and moreover $\hat{\mu}(I_D) = 1$. Now, note that since the diagonal D is a compact set, then any continuous function $A : G \rightarrow \mathbb{C}$ has a maximum at D , therefore (41) is well defined for continuous function. $\hat{\mu}$ is also well defined on the C^* -algebra. □

Definition 33. *A probability ν on Ω is called a **KMS probability** for the modular function V if the state $\hat{\nu}$ on $C_r^*(G)$ defined by*

$$\hat{\nu}(A) = \int A(x, x) \nu(dx) \quad (42)$$

satisfies the KMS condition for V . Here G is the groupoid given by the homoclinic equivalence relation.

This probability is sometimes called quasi-stationary (see [5]).

The next claim was proved on [20]. For completeness we will present a proof of this claim with full details.

Theorem 34. *If the probability α on Ω is a C^* -Gibbs probability with respect to V and β , then, $\hat{\alpha}$ is a KMS probability for the modular function βV . The associated $\hat{\alpha}$ is a C^* dynamical state for the $C_r^*(G)$ algebra given by the groupoid obtained by the homoclinic equivalence relation and satisfies the KMS boundary condition.*

Proof: Suppose α is a C^* -Gibbs state with respect to βV . We assume $\beta = 1$.

$\hat{\alpha}$ is σ^t invariant if for all $t \in \mathbb{C}$ it's true that

$$\int \sigma^t A(x, x) \alpha(dx) = \int A(x, x) \alpha(dx)$$

which by definition (39) it's equivalent to

$$\int e^{iV(x,x)t} A(x, x) \alpha(dx) = \int A(x, x) \alpha(dx)$$

but since $V(x, x) = 0$ then the state have to be σ^t invariant.

Now we will show that if $A, B \in \mathcal{C}_c(G)$, then

$$\hat{\alpha}(\sigma^t A * B) = \int \alpha(dx) \sum_{y \in [x]} e^{iV(x,y)t} A(x, y) \cdot B(y, x)$$

extends to an entire function (just change t to $z \in \mathbb{C}$). For this purpose we will pick $t_0 \in \mathbb{C}$ and show that

$$\lim_{t \rightarrow t_0} \frac{\hat{\alpha}(\sigma^t A * B) - \hat{\alpha}(\sigma^{t_0} A * B)}{t - t_0} \quad (43)$$

exist. Indeed, the limit (43) is equivalent to

$$\begin{aligned} & \lim_{t \rightarrow t_0} \frac{1}{t - t_0} \left(\int \alpha(dx) \sum_{y \in [x]} e^{iV(x,y)t} A(x, y) \cdot B(y, x) - \right. \\ & \quad \left. \int \alpha(ds) \sum_{y \in [s]} e^{iV(s,y)t_0} A(s, y) \cdot B(y, s) \right) = \\ & \lim_{t \rightarrow t_0} \left(\int \alpha(dx) \sum_{y \in [x]} \frac{(e^{iV(x,y)t} - e^{iV(x,y)t_0})}{t - t_0} A(x, y) \cdot B(y, x) \right). \quad (44) \end{aligned}$$

Always have in mind that for each x the summation is over finite terms.

Let R be a closed ball of radius 1 centered in t_0 . So we can consider the continuous function $f_{t_0} : R \setminus \{t_0\} \times \text{supp}(A) \rightarrow \mathbb{C}$

$$f_{t_0}(t, x) = \sum_{y \in [x]} \frac{(e^{iV(x,y)t} - e^{iV(x,y)t_0})}{t - t_0} A(x, y) \cdot B(y, x)$$

To extend f_{t_0} for the case $t = t_0$ we need to solve the limit

$$L_{t_0}(x) = \lim_{t \rightarrow t_0} \sum_{y \in [x]} \frac{(e^{iV(x,y)t} - e^{iV(x,y)t_0})}{t - t_0} A(x, y) \cdot B(y, x) = \quad (45)$$

$$\begin{aligned} & \sum_{y \in [x]} \lim_{t \rightarrow t_0} \frac{(e^{iV(x,y)t} - e^{iV(x,y)t_0})}{t - t_0} A(x, y) \cdot B(y, x) = \\ & \sum_{y \in [x]} iV(x, y) e^{iV(x,y)t_0} A(x, y) \cdot B(y, x). \end{aligned}$$

So define $f_{t_0}(t_0, x) = L_{t_0}(x)$.

In this way f_{t_0} is a continuous function defined on a compact domain. Therefore we may assume that both its real and imaginary parts are limited by a value M in the domain. Consider a sequence of functions indexed by the t variable, $\{f_{t_0}(t_n, x)\}_{n \in \mathbb{N}^*}$ that converge to $L_{t_0}(x)$ when $n \rightarrow \infty$, e.g. $f_{t_0}(t_0 + (1+i)/n, x)$. In this way the dominated convergence theorem assures that the limit (43) is equal to the integral:

$$\int \alpha(dx) L_{t_0}(x).$$

Indeed formally what we have is,

$$\begin{aligned} \int \alpha(dx) L_{t_0}(x) &= \int \alpha(dx) \sum_{y \in [x]} iV(x, y) e^{iV(x, y)t_0} A(x, y) \cdot B(y, x) = \\ &= \int \alpha(dx) \lim_{n \rightarrow \infty} \sum_{y \in [x]} \frac{(e^{iV(x, y)t_n} - e^{iV(x, y)t_0})}{t_n - t_0} A(x, y) \cdot B(y, x) = \\ &= \lim_{n \rightarrow \infty} \int \alpha(dx) \sum_{y \in [x]} \frac{(e^{iV(x, y)t_n} - e^{iV(x, y)t_0})}{t_n - t_0} A(x, y) \cdot B(y, x) = \\ &= \lim_{n \rightarrow \infty} \frac{\hat{\alpha}(\sigma^{t_n} A * B) - \hat{\alpha}(\sigma^{t_0} A * B)}{t_n - t_0} \end{aligned} \quad (46)$$

Now since the sequence was arbitrary we could remake these calculations to any desired convergent sequence with the same result, therefore (46) is equal to

$$\lim_{t \rightarrow t_0} \frac{\hat{\alpha}(\sigma^t A * B) - \hat{\alpha}(\sigma^{t_0} A * B)}{t - t_0},$$

what proves existence of the limit in equation (43). This allow us to conclude that $\hat{\alpha}(\sigma^t A * B)$ is an holomorphic function everywhere.

Let $F(t) = \hat{\alpha}(\sigma^t A * B)$. Using a partition of unity on $\text{supp } A$ we may write $A = \sum A_j$, where $\text{supp } A_j \subset W_j = \{(z, \varphi_j(z)) : z \in \mathcal{O}_j\}$, and $(\mathcal{O}_j, \varphi_j)$ is a conjugating homeomorphism. Since $\text{supp } A$ is a compact set then we may assume the summation to occur over a finite amount of elements. Thus

$$\begin{aligned} F(t) &= \int_{\Omega} \sum_j \alpha(dx) A_j(x, \varphi_j x) B(\varphi_j x, x) \exp(iV(x, \varphi_j x)t) = \\ &= \sum_j \int_{\mathcal{O}_j} \alpha(dx) A_j(x, \varphi_j x) B(\varphi_j x, x) \exp(iV(x, \varphi_j x)t) \end{aligned}$$

and therefore

$$F(t + i) = \sum_j \int_{\mathcal{O}_j} [e^{-V(x, \varphi_j x)} \alpha(dx)] A_j(x, \varphi_j x) B(\varphi_j x, x) \exp(iV(x, \varphi_j x)t)$$

If α is an C^* -Gibbs state by (5) we have that

$$\begin{aligned} F(t + \beta i) &= \sum_j \int_{\varphi_j(\mathcal{O}_j)} \alpha(dy) B(y, \varphi_j^{-1}y) A_j(\varphi_j^{-1}y, y) \exp(iV(\varphi_j^{-1}y, y)t) = \\ &= \sum_j \int_{\varphi_j(\mathcal{O}_j)} \alpha(dy) B(y, \varphi_j^{-1}y) \sigma^t A_j(\varphi_j^{-1}y, y) = \\ &= \int_{\Omega} \sum_j \alpha(dy) B(y, \varphi_j^{-1}y) \sigma^t A_j(\varphi_j^{-1}y, y) = \\ &= \int_{\Omega} \alpha(dy) (B * \sigma^t A)(y, y) = \hat{\alpha}(B * \sigma_t A) \end{aligned}$$

so that $\hat{\alpha}$ satisfies the KMS condition. □

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